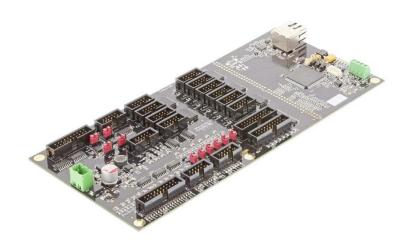


driving creation

Hardware Manual **CNC760**

Revision 5 23 October, 2018

Released



History:

| Revision | Date | Author |
|-------------|------------|--------|
| 1 | 22-5-2017 | AB |
| 2 23-6-2017 | | AB |
| 3 | 6-12-2017 | AB |
| 4 | 22-2-2018 | AB |
| 5 | 23-10-2018 | AB |
| | | |
| | | |

Revision overview:

| Revision | Remarks | | | | | |
|----------|---|--|--|--|--|--|
| 1 | Initial version. | | | | | |
| 2 | Fixed typo's in AUX-IN overview | | | | | |
| 3 | Correcting pinning HOME connector | | | | | |
| 4 | Correcting ALM+/- on axis outputs. Added clearifications. | | | | | |
| 5 | Added clearification about use of NPN/PNP home inputs | | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |

Table of contents

| 1 | Intro | oduction | 4 |
|---|-------|-------------------------------|----------|
| | 1.1 | Purpose | 4 |
| | 1.2 | Scope | 4 |
| 2 | Boa | rd overview | 5 |
| 3 | Boa | rd jumpers and indicators | 6 |
| | 3.1 | JP9, JP10, JP11 | 6 |
| | 3.2 | LED indications (LED2-LED6) | 7 |
| 4 | Con | nectors | <u>9</u> |
| | 4.1 | Power | <u>S</u> |
| | 4.2 | Network | 10 |
| | 4.3 | RS485 | 11 |
| | 4.4 | AUX-OUT | 12 |
| | 4.5 | AUX-IN | 15 |
| | 4.6 | CNC-OUT | 17 |
| | 4.7 | CNC-IN | 19 |
| | 4.8 | MPG | 22 |
| | 4.9 | HOME-IN | 24 |
| | 4.10 | PWM-OUT | 27 |
| | 4.11 | ANALOG-IN | 29 |
| | 4.12 | Extruder E1-E4 | 30 |
| | 4.13 | Axis A1-A6 | 32 |
| 5 | Con | figuring the analogue outputs | 38 |
| 6 | Gett | ring started | 30 |

1 Introduction

1.1 Purpose

This manual desribebdes the hardware of the CNC760.

The CNC760 is a 6-asix CNC controller with addional 4 extruder controllers. The basic specification is:

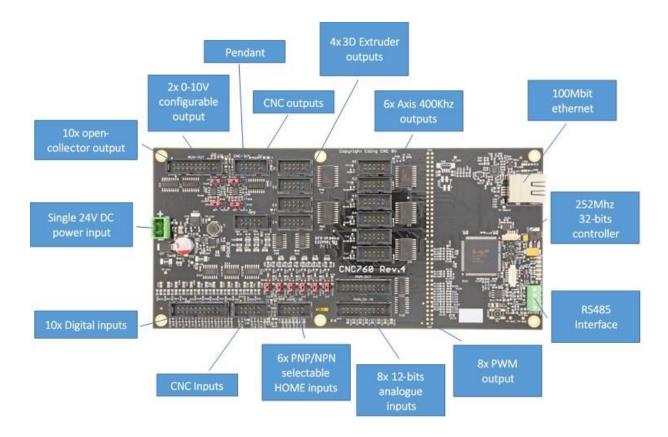
| | Puls/Direction | 5V (max. 400Khz) | |
|-----------------------------------|---|------------------------------------|--|
| 6x axis controller interface | • | · | |
| ox axis controller interface | Enable | 5V or open-collector (max. 24V) | |
| | Alarm | | |
| 4x extruder interface | Enable/Direction/Step | 5V | |
| 6x digital HOME inputs | 24V | | |
| 10x digital outputs | Open collector (max. 24 | 1V) | |
| 10x digital inputs | 24V | | |
| 8x analog inputs | 0-3.3v (12 bits) | | |
| 2x analog outputs | 0-10V | | |
| 2x cooling outputs | Open collector (max. 24 | ↓ ∨) | |
| 8x PWM outputs | Open collector (max. 24 | 1 V) | |
| | Output | Output for safety relay (Watchdog) | |
| | System Ready | Open Collector | |
| Safety relay I/O | Input | 24V | |
| Safety feldy 1/O | External Error | 24 V | |
| | Input | 24V | |
| | E-Stop | 241 | |
| 1x Length detection input (Probe) | 24V | | |
| 1x Spindle encoder input | 5V input | | |
| 1x RS485 interface | RS485, MODBUS compatible (for connecting extra I/O or | | |
| | functionality, cable leng | gth up to 20m) | |
| | 2x digital input | 5V | |
| Handwheel interface | 2x MPG input | 5V | |
| (Pendant) | 2x dedicated analog | 0-3.3V | |
| | input | U-5.5 V | |
| Interface | 100Mbit Ethernet | | |
| Power Supply | 24VDC | | |
| Dimension | 230x107mm (suitable for DIN rail mounting) | | |
| Others | Firmware upgradable through network connection | | |

1.2 Scope

This document describes the hardware of the CNC760.

2 Board overview

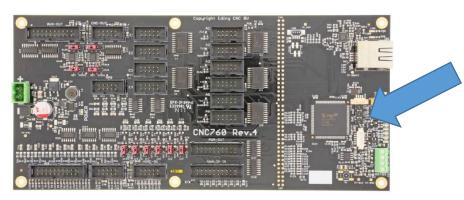
The image below shows an overview of the CNC760.



3 Board jumpers and indicators

3.1 JP9, JP10, JP11

With these jumpers, several settings can be forced:





JP9

JP10

IP11

| JP9 | Reserved |
|------|--|
| JP10 | Startup with default IP address 172.22.2.100 |
| JP11 | Skip bootloader |

3.2 LED indications (LED2-LED6)

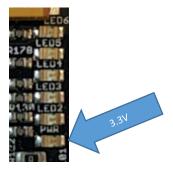
The board uses several LEDs indicating activity.



Power LEDs:



LED1: indicates that the external power is connected, this means that 24V and 5V are available.



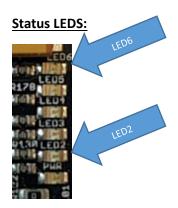
PWR: this LED indicates that the power for the processor is available (3.3V).

Network LEDs:



Yellow = Network activity

Green = Network connection



| LED6 | RED | SYSREADY, indicates when CNC system is ready for operation. Can be used in cooperation with safety relay. |
|------|-------|---|
| LED5 | RED | WATCHDOG charge pump, indicates operation of the watchdog circuitry |
| LED4 | GREEN | Controller 'heartbeat' indicating the board is active |
| LED3 | GREEN | Indicates 'Machine On' |
| LED2 | GREEN | Flashing when application is starting up. |
| | | After startup, will be switch ON if E-STOP occurred. |

Please note, when in bootloader mode LED2 and LED3 will toggle to indicate this.

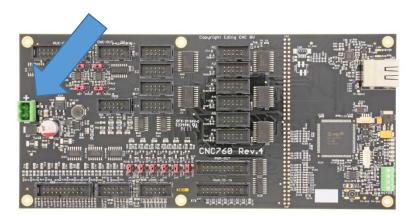
4 Connectors

4.1 Power

The voltage of the supplied power is 24V DC.

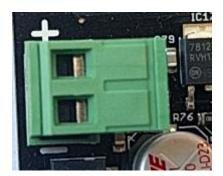
Warning: Due to a protection diode at the input the 24V that is available on a number of connectors will be a bit lower, please check when connecting 24V devices to that connector if they will operate correctly.

Warning: Although the 24V is also available on numerous connectors, it is advisable to use separate wiring for powering 24V devices if much current is needed.



The image below shows the power connector.





Warning: Check the polarity of the power, damage to the board may occur if the polarity is reversed.

4.2 Network

The board needs to be connected via *cross* cable of type CAT5 or CAT5E. We advise to use properly shielded network cables type SF/UTP. The default IP address is 172.22.2.100.



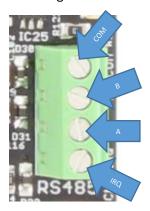
Note: Make sure that the PC that the board is connected to is correctly setup and has the correct IP address, make sure there is no IP address conflict.

4.3 RS485

Via the RS485 connector external hardware can be connected. RS485 is a balanced signal, this decreases susceptibility to interference. The protocolled that is used is MODBUS.



The image below shows a close up of the connector.



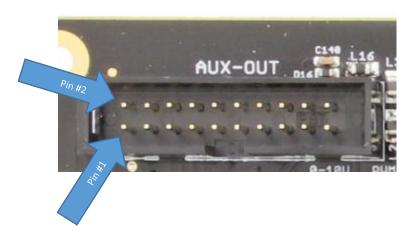
The connector consists out of 4 signals:

| COM | Common | |
|-----|----------|------------------------------|
| В | Balanced | |
| Α | signal | |
| IRQ | IRQ | Input for external interrupt |

4.4 AUX-OUT

The auxiliary outputs can be used for switching external devices.





Below an overview of all connections of this connector:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|-----------|-----------|----------------|-------------------------|-----------------------------|--|
| 1 | GND | | GROUND | | | |
| 2 | GND | | GROUND | | | |
| 3 | AUX OUT1 | OUTPUT | Open Collector | Aux Output 1 | Max. rating 50V/500mA | Optional used for controlling 0-10V output1 |
| 4 | SYSRDY | OUTPUT | Open Collector | System Ready | Max. rating 50V/500mA | System Ready, indicates that system is ready for operation. |
| 5 | AUX OUT2 | OUTPUT | Open Collector | Aux Output 2 | Max. rating 50V/500mA | Optional used for controlling 0-10V output2 |
| 6 | AUX OUT9 | OUTPUT | Open Collector | Aux Output 9 | Max. rating 50V/500mA | Shared with AEE3 |
| 7 | AUX OUT3 | OUTPUT | Open Collector | Aux Output 3 | Max. rating 50V/500mA | |
| 8 | AUX OUT10 | OUTPUT | Open Collector | Aux Output 10 | Max. rating 50V/500mA | Shared with AEE4 |
| 9 | AUX OUT4 | OUTPUT | Open Collector | Aux Output 4 | Max. rating 50V/500mA | |
| 10 | GND | | GROUND | | | |
| 11 | AUX OUT5 | OUTPUT | Open Collector | Aux Output 5 | Max. rating 50V/500mA | |
| 12 | GND | | GROUND | | | |
| 13 | AUX OUT6 | OUTPUT | Open Collector | Aux Output 6 | Max. rating 50V/500mA | |
| 14 | GND | | GROUND | | | |
| 15 | AUX OUT7 | OUTPUT | Open Collector | Aux Output 7 | Max. rating 50V/500mA | Shared with AEE1 |
| 16 | PWM-VOLT2 | OUTPUT | PW | /M or 0-10V, see also ' | Configuring the analogue ou | tputs' |
| 17 | AUX OUT8 | OUTPUT | Open Collector | Aux Output 8 | Max. rating 50V/500mA | Shared with AEE2 |
| 18 | GND | | GROUND | | | |
| 19 | +24V | | POWER | | +24V/1A | |
| 20 | +24V | | POWER | | +24V/1A | |

Warning: The total combined current of the 24V outputs should not exceed 1A

The auxiliary outputs are *open-collector* outputs. An open-collector output means it switches the connected wire to GND. This enables the user to switch devices that do not need the same voltage rating as the controller has.

In the image below such an output is shown.

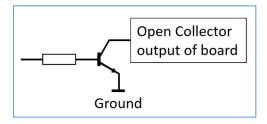


Figure 1 Open collector output.

This output can directly be used, for example, to switch a relay. If a logic signal is needed a pull-up resistor is required.

Please note, an open-collector output *can not* be measured with eg. a multimeter, to test an output connected a 10k resistor between output and +5V or 24V, now you should be able to measure this output switching.

Warning: Connecting an open-collector output directly to a positive voltage eg. 24V will cause a short-circuit damaging the board.

The drawing below shows how an open-collector output connector can be used to create different output signal levels by using a pull-up resistor. The value of this resistor can vary depending on the load of the output. Typical values are 4.7k or 10k.

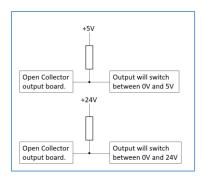


Figure 2 Creating different output levels with open-collector output.

With open-collector output it is very simple to use a relay in order to switch bigger loads. Connecting a relay is shown in the drawing below.

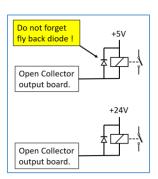


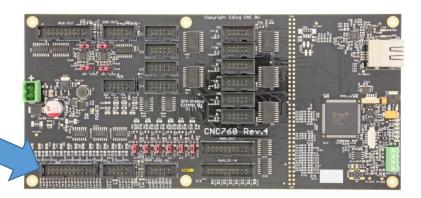
Figure 3 Connecting a relay to an open collector output.

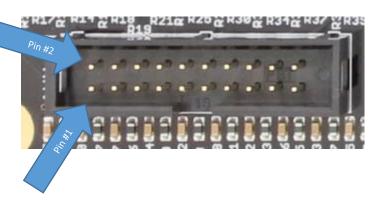
In the above example a 5V relay and 24V relay is used, both will switch. However please consider that a 5V relay will need more current to switch. This can limit the total number of used relays because of the maximum total current that can be switched.

Also, <u>VERY important</u> is it to use a fly back diode. This is necessary to limit spikes that occur when switching a relay. A typical diode that is used is e.g. 1N4007.

4.5 AUX-IN

The auxiliary inputs are digital inputs, used to retrieve the status of an external signal, for example a switch.





Each input has a pull-down, this means that when no signal is connector the board will see a 'low' signal. Connecting an input to 24V will cause the board to detect an 'high' signal.

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|----------|-----------|------------|--------------|-------------------|---------|
| 1 | GND | | GROUND | | | |
| 2 | GND | | GROUND | | | |
| 3 | AUX IN1 | INPUT | Digital in | Aux Input 1 | Input voltage 24V | |
| 4 | GND | | GROUND | | | |
| 5 | AUX IN2 | INPUT | Digital in | Aux Input 2 | Input voltage 24V | |
| 6 | AUX IN9 | INPUT | Digital in | Aux Input 9 | Input voltage 24V | |
| 7 | AUX IN3 | INPUT | Digital in | Aux Input 3 | Input voltage 24V | |
| 8 | AUX IN10 | INPUT | Digital in | Aux Input 10 | Input voltage 24V | |
| 9 | AUX IN4 | INPUT | Digital in | Aux Input 4 | Input voltage 24V | |
| 10 | GND | | GROUND | | | |
| 11 | AUX IN5 | INPUT | Digital in | Aux Input 5 | Input voltage 24V | |
| 12 | GND | | GROUND | | | |
| 13 | AUX IN6 | INPUT | Digital in | Aux Input 6 | Input voltage 24V | |
| 14 | GND | | GROUND | | | |
| 15 | AUX IN7 | INPUT | Digital in | Aux Input 7 | Input voltage 24V | |
| 16 | GND | | GROUND | | | |
| 17 | AUX IN8 | INPUT | Digital in | Aux Input 8 | Input voltage 24V | |
| 18 | GND | | GROUND | | | |
| 19 | +24V | | POWER | | +24V/1A | |
| 20 | +24V | | POWER | | +24V/1A | |

Warning: The total combined current of the 24V outputs should not exceed 1A

In the image below, you see the input circuit for each AUX input.

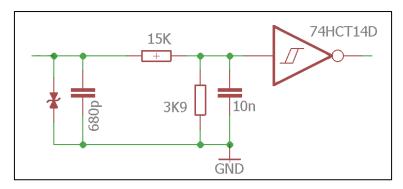


Figure 4. AUX input circuit.

The image shows how to connect a switch to an AUX input:

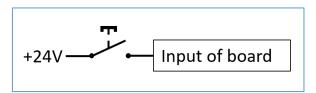
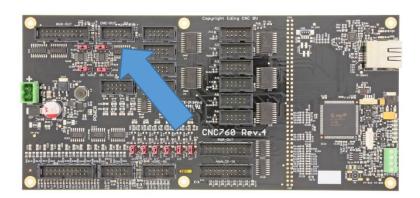
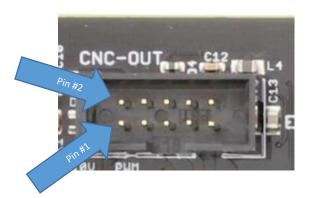


Figure 5 Connecting a switch to an AUX input.

4.6 CNC-OUT

The CNC-OUT signals are output signals and are typical related to controlling the CNC functionality.





Below an overview of all connections of this connector:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks | | |
|------|-------------|-----------|----------------|---|-----------------------|--|--|--|
| 1 | PWM-VOLT1 | Output | PV | PWM or 0-10V, see also 'Configuring the analogue outputs' | | | | |
| 2 | SYSRDY | Output | Open Collector | System Ready | Max. rating 50V/500mA | System Ready, indicates that system is ready for operation. | | |
| 3 | TOOLON | Output | Open Collector | Switch tool ON (eg. Spindle) | Max. rating 50V/500mA | | | |
| 4 | TOOLDIR | Output | Open Collector | Set tool direction | Max. rating 50V/500mA | | | |
| 5 | COOL2 | Output | Open Collector | Coolant2 signal | Max. rating 50V/500mA | | | |
| 6 | COOL1 | Output | Open Collector | Coolant1 signal | Max. rating 50V/500mA | | | |
| 7 | +24V | | Power | | +24V/1A | | | |
| 8 | Charge Pump | Output | Open Collector | Watchdog signal | Max. rating 50V/500mA | Pulsed signal | | |
| 9 | +5V | Output | Power | | 5VDC/500mA | | | |
| 10 | GND | | Ground | | | | | |

Warning: Connecting an open-collector output directly to a positive voltage eg. 24V will cause a short-circuit damaging the board.

Warning: The total combined current of the 24V outputs should not exceed 1A

In the image below such an output is shown. An open-collector output means it switches the connected wire to GND. This enables the user to switch devices that do not need the same voltage rating as the controller has.

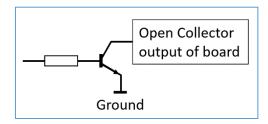


Figure 6 Open collector output.

The drawing below shows how an open-collector output connector can be used to create different output signal levels by using a pull-up resistor. The value of this resistor can vary depending on the load of the output. Typical values are 4.7k or 10k.

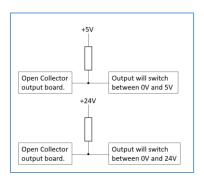


Figure 7 Creating different output levels with open-collector output.

With open-collector output it is very simple to use a relay in order to switch bigger loads. Connecting a relay is shown in the drawing below.

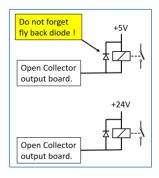


Figure 8 Connecting a relay to an open collector output.

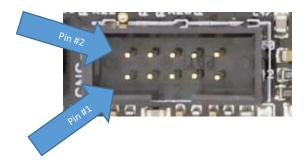
In the above example a 5V relay and 24V relay is used, both will switch. However please consider that a 5V relay will need more current to switch. This can limit the total number of used relays because of the maximum total current that can be switched.

Also, <u>VERY important</u> is it to use a fly back diode. This is necessary to limit spikes that occur when switching a relay. A typical diode that is used is e.g. 1N4007.

4.7 CNC-IN

The CNC-IN signals are CNC related inputs.





Below an overview of all connections of this connector:

| Pin # | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|-------|--------------|--------------|---------|--|---------------------------|--------------------|
| 1 | PROBE | Input | Digital | Input signal for external probe signal | Max. input voltage 24V | Active low |
| 2 | SPINDLEX | Input | Digital | | Max. input voltage 5V | Active low |
| 3 | ESTOP | Input | Digital | External EMERGENCY STOP signal | Max. Input voltage 24V | |
| 4 | EXTERR | Input | Digital | External ERROR signal | Max. Input voltage 24V | |
| 5 | PROBE | Input | Digital | | | Shared with pin #1 |
| 6 | SPINDLEA | Input | Digital | Signal A input | Max. Input voltage 5V | Active low |
| 7 | +24V | | POWER | | +24V/1A | |
| 8* | SPINDLEB/GND | Input/Ground | Digital | Signal B input | Max. Input voltage 5V | Active low |
| 9 | +24V | | POWER | | +24V/1A | |
| 10 | GND | | Ground | | | |

Warning: The total combined current of the 24V outputs should not exceed 1A.

Note, pin #8 can be connected to Ground for backward compatibility by removing resistor R167, and closing the pads of SJ1

Please not that PROBE, ESTOP and EXTERR requires input signals of 24V, however SPINDLEX, SPINDLEA and SPINDLEB have *maximum* input levels of 5V, and are damaged if 24V is connected.

Below the input circuit is shown for both types:

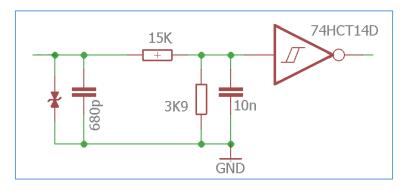


Figure 9 Input circuit of PROBE, ESTOP, EXTERR.

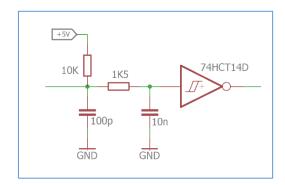


Figure 10 Input circuit SPINDLEX, SPINDLEA and SPINDLEB.

For using the PROBE, ESTOP or EXTERR the input signal needs to switch to 24V, in the image below this is shown.

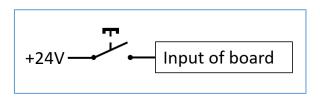


Figure 11. Input signal for PROBE, ESTOP and EXTERR.

Using SPINDLEX, SPINDLEA, SPINDLEB the input signal needs to to ground to be active. The image below shows this.

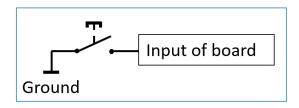
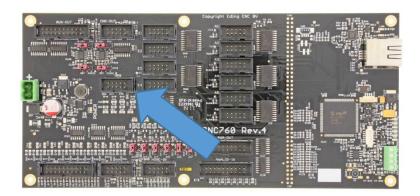
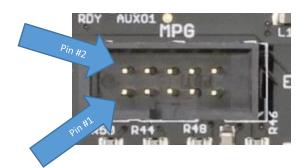


Figure 12 Input signal for SPINDLEX, SPINDLEA and SPINDLEB.

4.8 MPG

The MPG connectors makes it possible to connect directly a wired pendant to the controller.





Below an overview of all connections of this connector:

| Pin# | Name | Direction | Type | Function | Electrical Spec. | Remarks |
|------|-------|-----------|----------|--|----------------------------|--|
| 1 | AN7 | Input | Analogue | Analogue input for additional selections | Max. Input voltage 3.3V | This is actual AN7, so not an extra analog input |
| 2 | PAUSE | Input | Digital | Pause switch | Max. Input Voltage 5V | Active low |
| 3 | HW-A | Input | Digital | Handwheel A input | Max. Input voltage 5V | |
| 4 | RUN | Input | Digital | Run switch | Max. Input voltage 5V | Active low |
| 5 | HW-B | Input | Digital | Handwheel B input | Max. Input voltage 5V | |
| 6 | AN8 | Input | Analogue | Analogue input for additional selections | Max. Input voltage 3.3V | This is actual AN8, so not an extra analog input |
| 7 | +3.3V | Output | Power | | +3.3V/100mA | |
| 8 | GND | | Ground | | | |
| 9 | +5V | Output | Power | | +5V/500mA | |
| 10 | GND | | Ground | | | |

Note, 3.3V on pin #7 not present on revision 4 of hardware.

The analogue inputs AN7 & AN8 can be used to have extra selection for axis and multiplication factor.

In the image below is a schematic of each *digital* input:

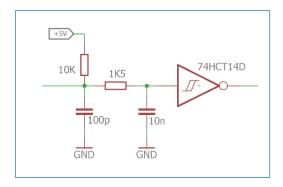


Figure 13 Pendant digital inputs schematic.

Using the PAUSE or RUN input is simply connecting a push button to it, with one side connected to GROUND and the other to the input of the board.

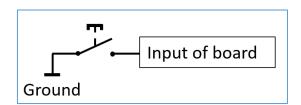
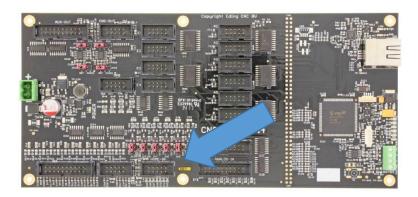


Figure 14 Connecting switch to PAUSE or RUN input.

4.9 HOME-IN

The HOME inputs are required for the machine to be able to detect the 'home' position.





Below an overview of all connections of this connector:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|----------|-----------|---------|--------------|---------------------------|----------------|
| 1 | HOME1 | Input | Digital | Home input 1 | Max. input Voltage 24V | |
| 2 | HOME4 | Input | Digital | Home input 4 | Max. input Voltage 24V | |
| 3 | HOME2 | Input | Digital | Home input 2 | Max. input Voltage 24V | |
| 4 | HOME5 | Input | Digital | Home input 5 | Max. input Voltage 24V | |
| 5 | HOME3 | Input | Digital | Home input 3 | Max. input Voltage 24V | |
| 6 | HOME6 | Input | Digital | Home input 6 | Max. input Voltage 24V | |
| 7 | +24V | | POWER | | +24V/1A | |
| 8 | GND | | Ground | | | |
| 9 | Reserved | | | | | Do not connect |
| 10 | GND | | Ground | | | |

Warning: The total combined current of the 24V outputs should not exceed 1A.

The home-input can be configured into two modes, each mode describes what type of switch or sensor is connected. If the switch or sensor is activated, it means that it will switch either to ground (OV) or to a voltage, in this case 24V. A switch or sensor that switches to 0 (negative) is called NPN, a switch or sensor that switches to 24V (positive) is called PNP.

PNP = Input should be 'HIGH' (24V) to detect the switch/sensor being activated.

NPN = Input should be 'LOW' (0V) to detect the switch/sensor being activated.

Please note, that ALL home inputs are **EITHER** NPN or PNP. Currently it is **not possible** to mix the inputs types.

This mode selection is done via several jumpers:



The default settings are NPN.

Each jumper corresponds to an input:

| Jumper | Input |
|--------|--------------|
| JP2 | Home input 1 |
| JP3 | Home input 2 |
| JP4 | Home input 3 |
| JP5 | Home input 4 |
| JP6 | Home input 5 |
| JP7 | Home input 6 |

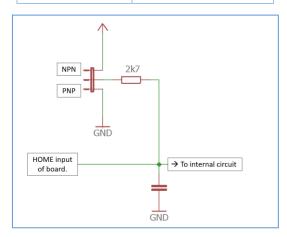


Figure 15 Input circuit of HOME input.

Switching in NPN mode:

When in NPN mode the input needs to switch to ground to be activated.

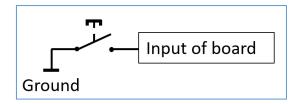
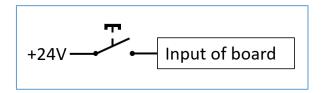


Figure 16 Switching HOME input in NPN mode.

Switchting in PNP mode:

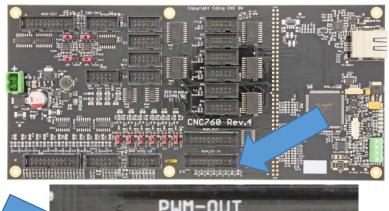
When in PNP mode the inputs need to switch to +24V to be activated.



 ${\it Figure~17~Switching~HOME~input~in~PNP~mode}.$

4.10 PWM-OUT

The PWM outputs enable the user to add extra control of devices that use PWM signals for control.





Below an overview of all connections of this connector:

| Pin# | Name | Direction | Type | Function | Electrical Spec. | Remarks |
|------|--------|-----------|----------------|--------------|-----------------------|--|
| 1 | GND | | Ground | | | |
| 2 | GND | | Ground | | | |
| 3 | PWM1 | Output | Open Collector | PWM Output 1 | Max. rating 50V/500mA | Also used for generating 0-10V output1 |
| 4 | SYSRDY | Output | Open Collector | System Ready | Max. rating 50V/500mA | System Ready, indicates that system is ready for operation. |
| 5 | PWM2 | Output | Open Collector | PWM Output 2 | Max. rating 50V/500mA | Also used for generating 0-10V output2 |
| 6 | GND | | Ground | | | |
| 7 | PWM3 | Output | Open Collector | PWM Output 3 | Max. rating 50V/500mA | |
| 8 | GND | | Ground | | | |
| 9 | PWM4 | Output | Open Collector | PWM Output 4 | Max. rating 50V/500mA | |
| 10 | GND | | Ground | | | |
| 11 | PWM5 | Output | Open Collector | PWM Output 5 | Max. rating 50V/500mA | |
| 12 | GND | | Ground | | | |
| 13 | PWM6 | Output | Open Collector | PWM Output 6 | Max. rating 50V/500mA | |
| 14 | GND | | Ground | | | |
| 15 | PWM7 | Output | Open Collector | PWM Output 7 | Max. rating 50V/500mA | |
| 16 | GND | | Ground | | | |
| 17 | PWM8 | Output | Open Collector | PWM Output 8 | Max. rating 50V/500mA | |
| 18 | GND | | Ground | | | |
| 19 | +24V | | POWER | | +24V/1A | |
| 20 | +24V | | POWER | | +24V/1A | |

Warning: Connecting an open-collector output directly to a positive voltage eg. 24V will cause a short-circuit damaging the board.

Warning: The total combined current of the 24V outputs should not exceed 1A

The PWM outputs are *open-collector* outputs. An open-collector output means it switches the connected wire to GND. This enables the user to switch devices that do not need the same voltage rating as the controller has.

In the image below such an output is shown.

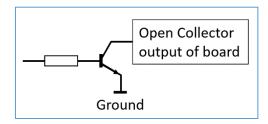


Figure 18 Open collector output.

This output can directly be used, or if a logic signal is needed a pull-up resistor is required.

Please note, an open-collector output can not be measured with eg. a multimeter, to test an output connected a 10k resistor between output and +5V or 24V, now you should be able to measure this output switching.

Warning: Connecting an open-collector output directly to a positive voltage eg. 24V will cause a short-circuit damaging the board.

The drawing below shows how an open-collector output connector can be used to create different output signal levels by using a pull-up resistor. The value of this resistor can vary depending on the load of the output. Typical values are 4.7k or 10k.

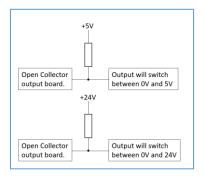
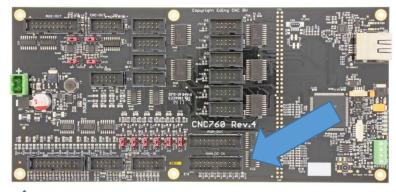


Figure 19 Creating different output levels with open-collector output.

4.11 ANALOG-IN

The analog inputs can be used to capture input voltages. The maximum voltage is 3.3V, make sure you do not exceed this limit as it will damage this input, or even the rest of the board.





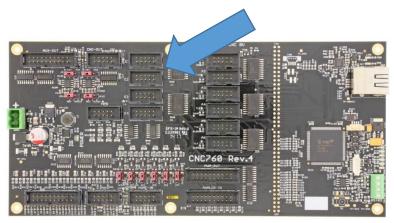
Below an overview of all connections of this connector:

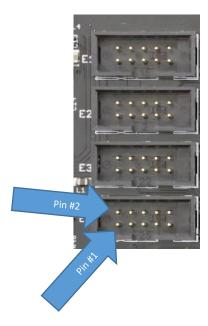
| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|----------|-----------|----------|-----------------|----------------------------|-----------------------------------|
| 1 | GND | | Ground | Ground | | |
| 2 | GND | | Ground | Ground | | |
| 3 | AN1 | Input | Analogue | Analoge input 1 | Max. input voltage 3.3V | Pulled down with 100k resistor |
| 4 | Reserved | | | | | Do not connect |
| 5 | AN2 | Input | Analogue | Analoge input 2 | Max. input voltage 3.3V | Pulled down with 100k resistor |
| 6 | GND | | Ground | Ground | | |
| 7 | AN3 | Input | Analogue | Analoge input 3 | Max. input voltage 3.3V | Pulled down with 100k resistor |
| 8 | GND | | Ground | Ground | | |
| 9 | AN4 | Input | Analogue | Analoge input 4 | Max. input voltage 3.3V | Pulled down with 100k resistor |
| 10 | GND | | Ground | Ground | | |
| 11 | AN5 | Input | Analogue | Analoge input 5 | Max. input voltage 3.3V | Pulled down with 100k resistor |
| 12 | GND | | Ground | Ground | | |
| 13 | AN6 | Input | Analogue | Analoge input 6 | Max. input voltage 3.3V | Pulled down with 100k resistor |
| 14 | GND | | Ground | Ground | | |
| 15 | AN7 | Input | Analogue | Analoge input 7 | Max. input voltage 3.3V | Pulled down with 100k resistor |
| 16 | GND | | Ground | Ground | | |
| 17 | AN8 | Input | Analogue | Analoge input 8 | Max. input voltage 3.3V | Pulled down with 100k resistor |
| 18 | GND | | Ground | Ground | | |
| 19 | +24V | | POWER | | +24V/1A | |
| 20 | AVDD | Output | Power | | +3.3V/100mA | |

Warning: The total output current of pin #19 should not exceed 1A.

4.12 Extruder E1-E4

The extruder outputs can be used in 3D printer applications, controlling up to 4 extruders. The four outputs are designated E1 to E4.





On the next page all signals for the extruders are shown.

Note, the enable output for each of the 4 extruders are shared with an AUX OUT output, please check in your application that no pinning conflicts occurs!

Note, the step and direction signal for each extruder is combined with these signals for axis 6

Below an overview of the 4 extruder connectors:

Extruder 1:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|--------|-----------|---------|------------------------------|---------------------|----------------------|
| 1 | AEE1 | Output | Digital | Extruder enable E1 | 5V/15mA | Shared with AUX OUT7 |
| 2 | GND | | Ground | | | |
| 3 | DIRE1 | Output | Digital | Extruder direction signal E1 | 5V/15mA | Shared with DIR6 |
| 4 | GND | | Ground | | | |
| 5 | STEPE1 | Output | Digital | Extruder step signal E1 | 5V/15mA | Shared with STEP6 |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | GND | | Ground | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | GND | | Ground | | | |

Extruder 2:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|--------|-----------|---------|------------------------------|---------------------|----------------------|
| 1 | AEE2 | Output | Digital | Extruder enable E2 | 5V/15mA | Shared with AUX OUT8 |
| 2 | GND | | Ground | | | |
| 3 | DIRE2 | Output | Digital | Extruder direction signal E2 | 5V/15mA | Shared with DIR6 |
| 4 | GND | | Ground | | | |
| 5 | STEPE2 | Output | Digital | Extruder step signal E2 | 5V/15mA | Shared with STEP6 |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | GND | | Ground | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | GND | | Ground | | | |

Extruder 3:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|--------|-----------|---------|------------------------------|---------------------|-------------------------|
| 1 | AEE3 | Output | Digital | Extruder enable E3 | 5V/15mA | Shared with AUX OUT9 |
| 2 | GND | | Ground | | | |
| 3 | DIRE3 | Output | Digital | Extruder direction signal E3 | 5V/15mA | Shared with DIR6 |
| 4 | GND | | Ground | | | |
| 5 | STEPE3 | Output | Digital | Extruder step signal E3 | 5V/15mA | Shared with STEP6 |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | GND | | Ground | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | GND | | Ground | | | |

Extruder 4:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|--------|-----------|---------|------------------------------|---------------------|-----------------------|
| 1 | AEE4 | Output | Digital | Extruder enable E4 | 5V/15mA | Shared with AUX OUT10 |
| 2 | GND | | Ground | | | |
| 3 | DIRE4 | Output | Digital | Extruder direction signal E4 | 5V/15mA | Shared with DIR6 |
| 4 | GND | | Ground | | | |
| 5 | STEPE4 | Output | Digital | Extruder step signal E4 | 5V/15mA | Shared with STEP6 |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | GND | | Ground | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | GND | | Ground | | | |

Warning: The total combined output current of pin #9 of the extruders should not exceed 500mA.

4.13 Axis A1-A6

These outputs can control up to 6 axis simultaneously, these output are designated A1 to A6. Beside the step and direction signal each output has several extra signals.





Below an overview of the 6 axis connectors:

Axis 1:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|----------|-----------|----------------|--------------------|-----------------------|--------------------|
| 1 | ENABLE1 | Output | Digital | Amplifier enable 1 | 5V/15mA | |
| 2 | ENABLE1 | Output | Open-collector | Amplifier enable 1 | Max. rating 40V/100mA | |
| 3 | DIR1 | Output | Digital | Direction signal 1 | 5V/15mA | |
| 4 | GND | | Ground | | | |
| 5 | STEP1 | Output | Digital | Step signal 1 | 5V/15mA | |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | DRV-ALM- | | | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | DRV-ALM+ | Input | Digital | Alarm input | | Pulled up with 4k7 |

Axis 2:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|----------|-----------|----------------|--------------------|-----------------------|--------------------|
| 1 | ENABLE1 | Output | Digital | Amplifier enable 1 | 5V/15mA | |
| 2 | ENABLE1 | Output | Open-collector | Amplifier enable 1 | Max. rating 40V/100mA | |
| 3 | DIR1 | Output | Digital | Direction signal 1 | 5V/15mA | |
| 4 | GND | | Ground | | | |
| 5 | STEP1 | Output | Digital | Step signal 1 | 5V/15mA | |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | DRV-ALM- | | | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | DRV-ALM+ | Input | Digital | Alarm input | | Pulled up with 4k7 |

Axis 3:

| Pin # | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|-------|----------|-----------|----------------|--------------------|-----------------------|--------------------|
| 1 | ENABLE1 | Output | Digital | Amplifier enable 1 | 5V/15mA | |
| 2 | ENABLE1 | Output | Open-collector | Amplifier enable 1 | Max. rating 40V/100mA | |
| 3 | DIR1 | Output | Digital | Direction signal 1 | 5V/15mA | |
| 4 | GND | | Ground | | | |
| 5 | STEP1 | Output | Digital | Step signal 1 | 5V/15mA | |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | DRV-ALM- | | | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | DRV-ALM+ | Input | Digital | Alarm input | | Pulled up with 4k7 |

Axis 4:

| Pin # | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|-------|----------|-----------|----------------|--------------------|-----------------------|--------------------|
| 1 | ENABLE1 | Output | Digital | Amplifier enable 1 | 5V/15mA | |
| 2 | ENABLE1 | Output | Open-collector | Amplifier enable 1 | Max. rating 40V/100mA | |
| 3 | DIR1 | Output | Digital | Direction signal 1 | 5V/15mA | |
| 4 | GND | | Ground | | | |
| 5 | STEP1 | Output | Digital | Step signal 1 | 5V/15mA | |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | DRV-ALM- | | | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | DRV-ALM+ | Input | Digital | Alarm input | | Pulled up with 4k7 |

Axis 5:

| Pin # | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|-------|----------|-----------|----------------|--------------------|-----------------------|--------------------|
| 1 | ENABLE1 | Output | Digital | Amplifier enable5 | 5V/15mA | |
| 2 | ENABLE1 | Output | Open-collector | Amplifier enable5 | Max. rating 40V/100mA | |
| 3 | DIR1 | Output | Digital | Direction signal 5 | 5V/15mA | |
| 4 | GND | | Ground | | | |
| 5 | STEP1 | Output | Digital | Step signal 5 | 5V/15mA | |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | DRV-ALM- | | | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | DRV-ALM+ | Input | Digital | Alarm input | | Pulled up with 4k7 |

Axis 6:

| Pin# | Name | Direction | Туре | Function | Electrical Spec. | Remarks |
|------|----------|-----------|----------------|--------------------|-----------------------|--------------------|
| 1 | ENABLE1 | Output | Digital | Amplifier enable 6 | 5V/15mA | |
| 2 | ENABLE1 | Output | Open-collector | Amplifier enable 6 | Max. rating 40V/100mA | |
| 3 | DIR1 | Output | Digital | Direction signal 6 | 5V/15mA | |
| 4 | GND | | Ground | | | |
| 5 | STEP1 | Output | Digital | Step signal 6 | 5V/15mA | |
| 6 | GND | | Ground | | | |
| 7 | GND | | Ground | | | |
| 8 | DRV-ALM- | | | | | |
| 9 | +5V | Output | Power | | +5V/500mA | See warning. |
| 10 | DRV-ALM+ | Input | Digital | Alarm input | | Pulled up with 4k7 |

Warning: The total combined output current of pin #9 of the axis should not exceed 500mA.

Each connecting has an alarm input is available. The alarm inputs pins of all axes are wired together. It is assumed that the alarm output of the drives are open-collector outputs so that the alarm outputs of all drives can be coupled together. So, each output can pull the alarm input low to generate an alarm.

Please check that the motor driver ALARM output is configured to be 'open' if not active.

The image below shows such a setup.

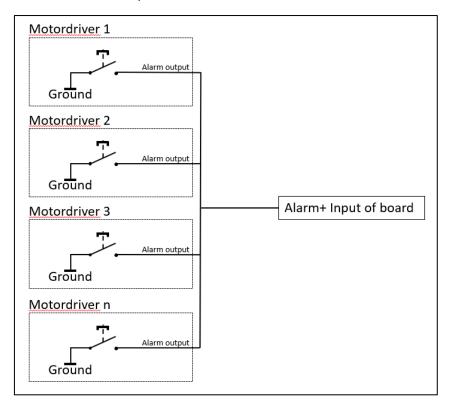


Figure 20 Combining open collector outputs of drivers.

Below is image that shows the input circuit of the alarm input. The alarm input is active if the DRVALM+ input is pulled low.

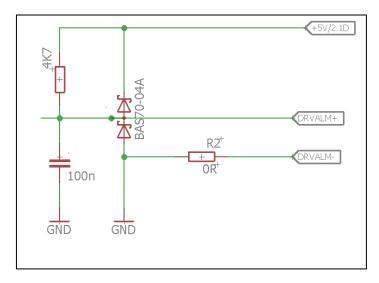


Figure 21 Alarm input circuit.

In the CNC.INI file the alarm input behavior needs to correctly defined. Please check that 'driveErrorInputSenseLevel' is set to '0'.

Warning: Make sure you test the alarm input before start to use it.

Each axis output has a two enable outputs, these signals are used to enable to motor driver. The difference between these two signals is that one signal is a digital +5V signal, and the other is an open-collector signal. This helps in connecting the controller to different kind of drives.

The enable signal with an open-collector output is able to switch higher voltages compared to the +5V output. In the image below such an output is shown. An open-collector output means it switches the connected wire to GND. This enables the user to switch devices that do not need the same voltage rating as the controller has.

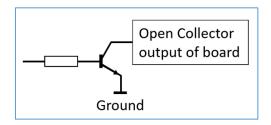


Figure 22 Open collector output.

The drawing below shows how an open-collector output connector can be used to create different output signal levels by using a pull-up resistor. The value of this resistor can vary depending on the load of the output. Typical values are 4.7k or 10k.

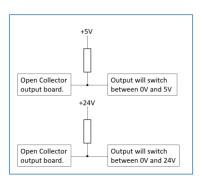


Figure 23 Creating different output levels with open-collector output.

With open-collector output it is very simple to use a relay in order to switch bigger loads. Connecting a relay is shown in the drawing below.

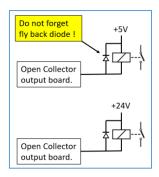


Figure 24 Connecting a relay to an open collector output.

In the above example a 5V relay and 24V relay is used, both will switch. However please consider that a 5V relay will need more current to switch. This can limit the total number of used relays because of the maximum total current that can be switched.

Also, <u>VERY important</u> is it to use a fly back diode. This is necessary to limit spikes that occur when switching a relay. A typical diode that is used is e.g. 1N4007.

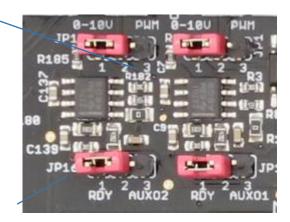
Look at the manual of your driver to see how it can be enabled.

5 Configuring the analogue outputs

The CNC760 board contains two identical 0-10V outputs. There are 2 jumpers for each output that can be used to configure the behaviour of these outputs.

Output selector:

0-10V or PWM



Output via SYSTEN READY or AUXOx

Output signal type:

The top jumper selects what signal is present on the output. Either 0-10V, which is default, or the standard PWM signal. These outputs use the existing PWM outputs of the board.

From the picture above, the left output (PWM-VOLT2) uses PWM2 output, the right output (PWM-VOLT1) uses PWM1 output.

When the PWMx output signal is selected it's identical to the PWMx signal on the PWM output connectors, that means that this signal is an open-collector output.

Warning: Connecting an open-collector output directly to a positive voltage eg. 24V will cause a short-circuit

Output enable behaviour:

The bottom jumper selects whether the output is enabled when the 'SYSTEM READY' is available, the default behaviour, or that it is controlled via an AUXOx output.

From the pictures above, the left output (PWM-VOLT2) uses AUXO2 output to control the output, the right output (PWM-VOLT1) uses AUXO1 output to control the output.

WARNING: If the jumper is set to enable the output via one of the AUXOx outputs, the 'SYSTEM READY' signal will no longer switch off this output.

6 Getting started

Before installing the board it's a clever idea to validate that the board is operational.

Validate the board

- Step 1. The first step is to validate the board is operational. Connect the network cross cable to the board and the PC. Make sure you have set the correct IP address on the PC. For a description on how to setup the PC please refer to the software manual.
- Step 2. Connect the power, as a result the two blue power leds should turn on. And observe that the status LEDs indicates that the board is active, indicated by the 'heart beat'.
- Step 3. Try to connect to the board.

The board is now able to communicate with the application software.

Check for motion

Now the board is operational the next step is to check whether the machine and home switches work correctly. We start with the homing switches. Make sure that the power is off.

- Step 1. The first step is to determine how to configure the jumpers. For now, the most important once are the jumpers for the home inputs. Set these jumpers to the correct position based on the type of the home switches used.
- Step 2. Power up the board and connect.
- Step 3. By using the I/O screen of the application validate that the switches are correctly detected; if you need to invert the signal do this in the setup of the software. If this is done, power down the board.
- Step 4. Connect the drivers to the board, you can choose to connect all motors at once or just one at a time. Please check the manual of the driver on how to connect it to the controllers, also check that the enable is correctly connected; directly or via the open-collector output. Some drivers will automatically be enabled when this input is not connected and they're power up.
- Step 5. DOUBLE check all connections.
- Step 6. Power up the board and driver(s) and connect to the board.
- Step 7. Normally with the default settings of the software you should be able to get some motion. If not please check the following:
 - Are all signals correctly connected?
 - Do some signals need to be inverted (eg. enable)?

TIP: By using the software I/O screen you can manually check the enabling of the drivers. When the drive is not enabled you will be able to move it by hand, if it is enabled this should not be possible.

If all went ok, your machine has now a basic setup. From here you can continue to connect more I/O to the board, please check all I/O via the software; also check whether inversion is necessary.

Please note that the system will need to be tuned to each specific machine. This means that machine parameters as speed/acceleration etc. will need to be changed to get optimum performance. Please make sure you know who to do this, and If not request support.

And finally perform each part of the setup step by step, so you know where to look in case something does not work immediately.